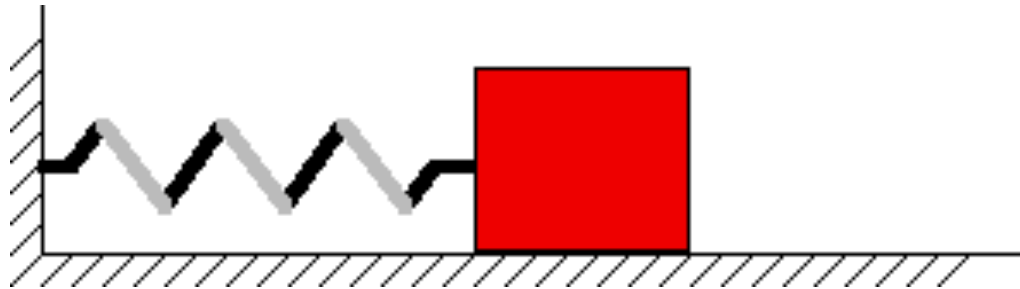


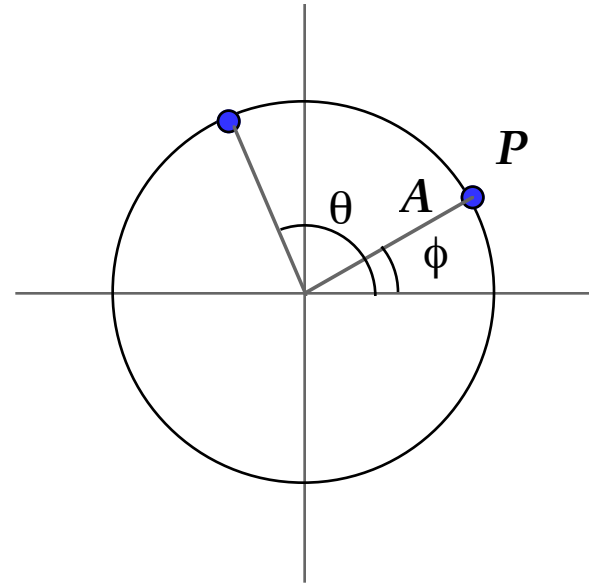
Ch 15

Simple Harmonic Motion



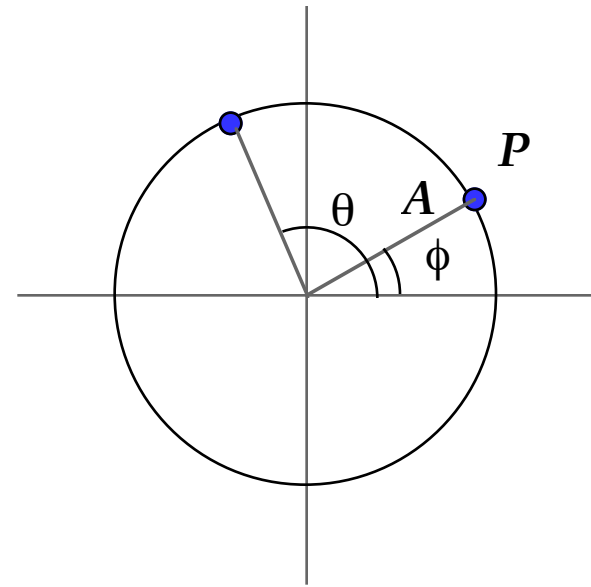
Periodic (Circular) Motion

Point P is travelling in a circle with a constant speed. How can we determine the x -coordinate of the point P in terms of other given quantities?



Periodic (Circular) Motion

- Point P is beginning its circular motion at an arbitrary angular position ϕ .
- As P rotates with some angular velocity ω , the angular position of P is given by $\theta = \omega t + \phi$.
- What is the x coordinate of P as it rotates around the circle?



$$x = A \cos \theta$$

$$x = A \cos(\omega t + \phi)$$

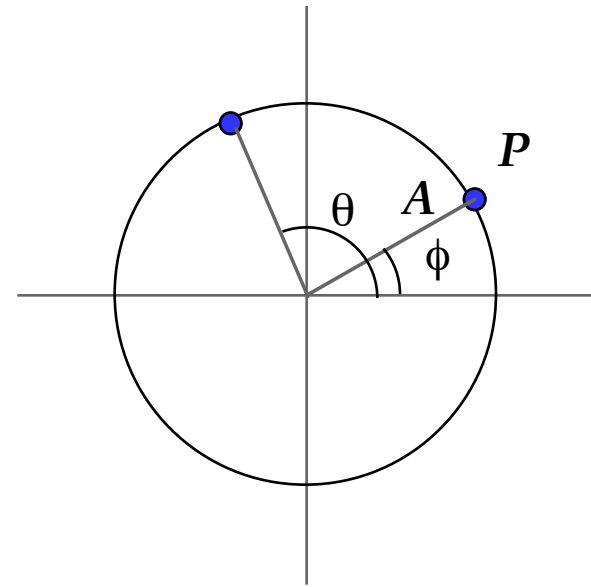
Vocabulary

A = the “amplitude” of the motion

T = the “period” = the time for one complete revolution

ω = the angular speed of P = “angular frequency”

ϕ = the “phase constant”



$$x = A \cos \theta$$

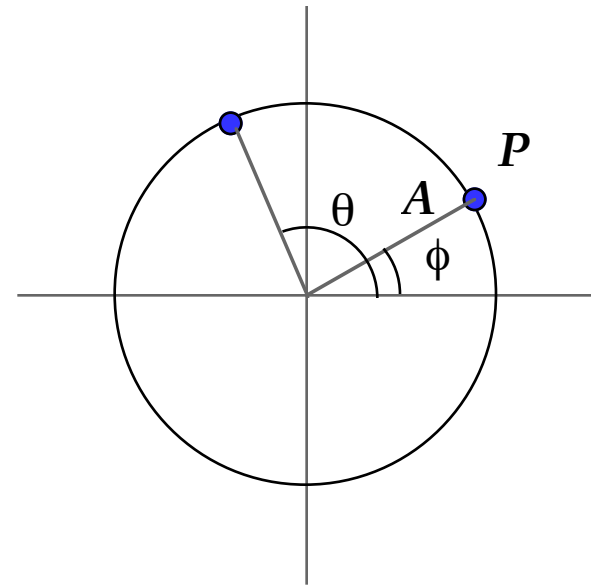
$$x = A \cos(\omega t + \phi)$$

S.H.M.

By definition, a particle on the x -axis exhibits simple harmonic motion when its position varies according to this relationship:

$$x = A \cos(\omega t + \phi)$$

x is a function of t , and repeats when ωt increases by 2π .

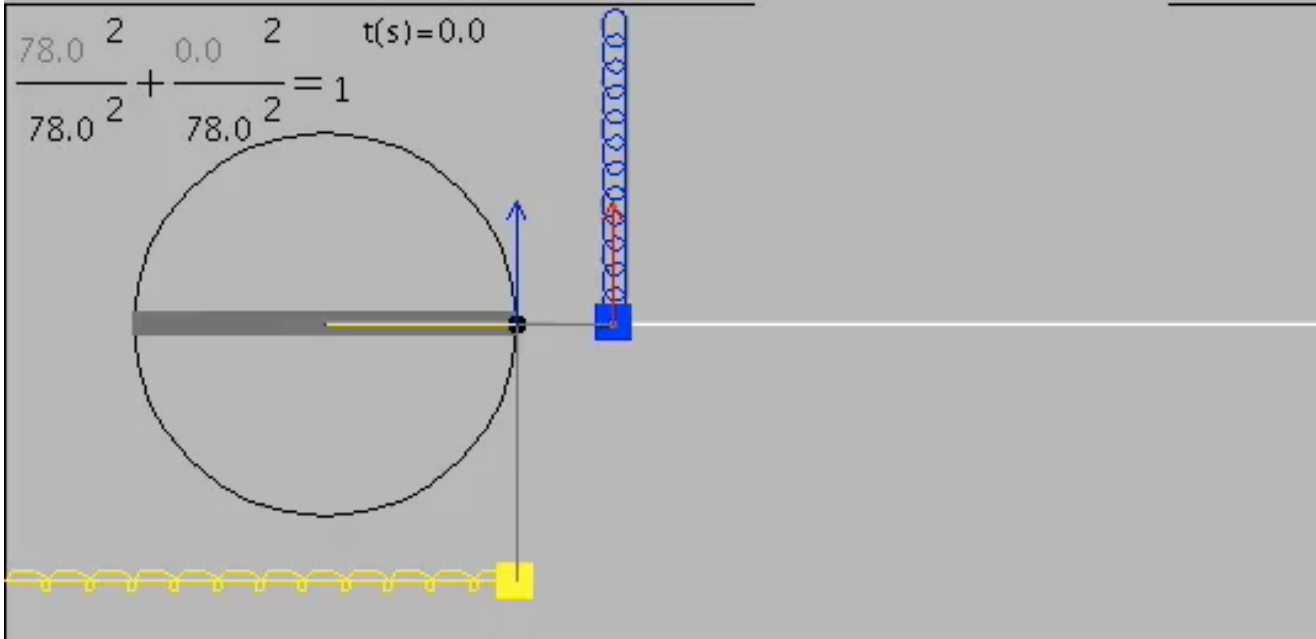


S.H.M.

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, x(t) = a * \sin(\omega t), y(t) = b * \cos(\omega t)$$

Reset

Start



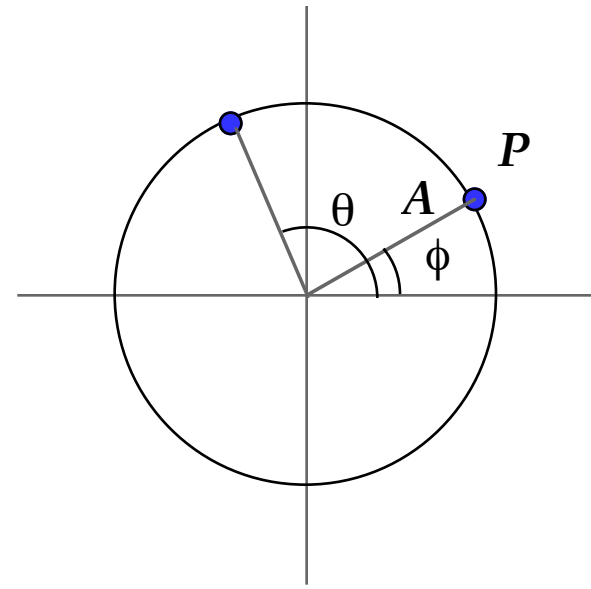
Frequency

What is the relationship
between T and ω ?

$$T = \frac{2\pi}{\omega}$$

The units for T are obviously “seconds” (per one cycle). If we invert T , we get *frequency* f , which is in “cycles per second,” or “Hertz.”

$$f = \frac{1}{T} = \frac{\omega}{2\pi}$$



$$x = A \cos(\omega t + \phi)$$

Derive $v(t)$?

$$x = A \cos(\omega t + \phi)$$

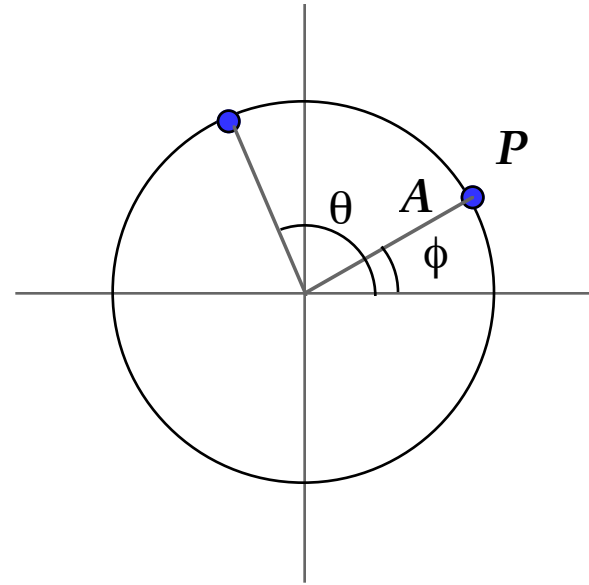
$$v = \frac{dx}{dt}$$

$$v = \frac{d}{dt}(A \cos(\omega t + \phi))$$

$$v = -\omega A \sin(\omega t + \phi)$$

And what is v 's maximum value?

$$v_{\max} = -\omega A$$



Derive $a(t)$?

$$a = -\omega A \sin(\omega t + \phi)$$

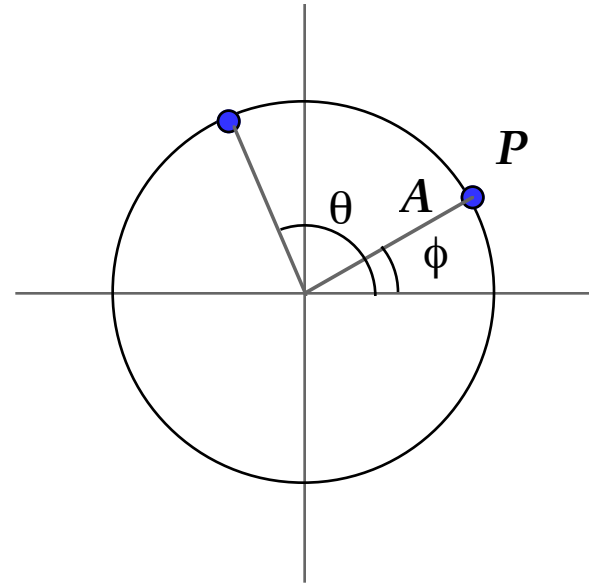
$$a = \frac{dv}{dt}$$

$$a = \frac{d}{dt}(-\omega A \sin(\omega t + \phi))$$

$$a = -\omega^2 A \cos(\omega t + \phi)$$

Note this important relationship:

$$a = -\omega^2 x$$



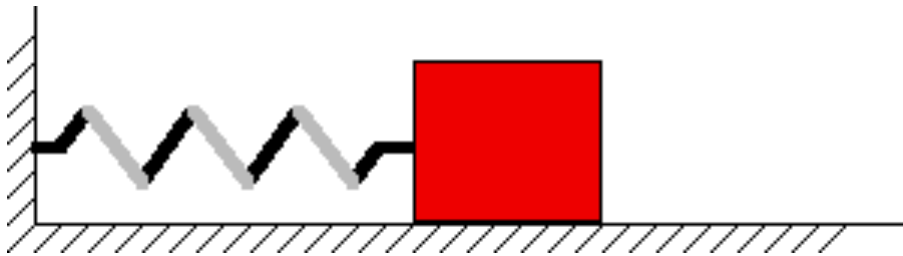
Example 1

Does the acceleration of a simple harmonic oscillator remain constant during its motion?

Is the acceleration of a simple harmonic oscillator ever zero?

Mass-Spring = SHM?

Do mass-spring systems exhibit SHM?
How would we know?



1. Assuming it's a Hooke's Law spring, we know that $F_{\text{spring}} = -kx$, or $ma = -kx$, or $a = -(k/m)x$, where k/m is a constant value.

2. We've already established, for SHM, that $a = -\omega^2 A \cos(\omega t + \phi)$, so
 $a = -\omega^2 x$

3. Therefore, if $-\omega^2 x = -(k/m)x$, our mass-spring system exhibits SHM.

***f* & *T* for Mass-Spring**

$$T = \frac{2\pi}{\omega}$$

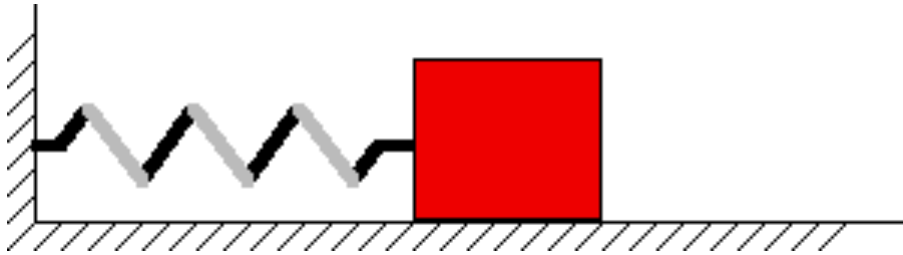
$$f = \frac{1}{T} = \frac{\omega}{2\pi}$$

$$T = \frac{2\pi}{\sqrt{\frac{k}{m}}} = 2\pi \sqrt{\frac{m}{k}}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

Mass-Spring Energy

$$E = U_{\max} = \frac{1}{2} kA^2$$



$$E = K_{\max} = \frac{1}{2} mv_o^2$$

$$E = \frac{1}{2} mv_x^2 + \frac{1}{2} kx^2$$

Example 2

A 5.00-kg mass is connected to a light spring with $k=20$ N/m, and oscillating on a horizontal frictionless surface.

- a. Calculate total energy of the system and speed of mass at x_0 if Amplitude is 3.00 cm.
- b. What is the velocity of the mass at $x=2.00$ cm?
- c. Find K & U when $x = 2.00$ cm
- d. For what values of x does the speed of the mass = 0.1 m/s?

The Simple Pendulum

... consists of a mass (a “bob”) at the end of a string of length L , swinging back and forth due to the effect of gravity.

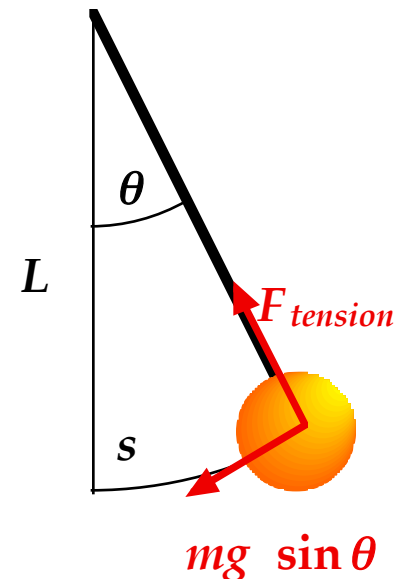


$$F_{\text{tangential}} = -mg \sin \theta = m \frac{d^2 s}{dt^2}$$

$$s = L\theta, \text{ so}$$

$$-g \sin \theta = \frac{d^2 L\theta}{dt^2}$$

$$\frac{d^2 \theta}{dt^2} = \frac{-g}{L} \sin \theta$$



Pendulum = SHM?

1. Set calculator mode to rads
2. Set graph range for 0-1, 0-1
3. Graph $y_1 = x$
4. Graph $y_2 = \sin x$

The Physical Pendulum

A physical pendulum includes a solid object of mass m that oscillates under the influence of gravity.

$$\tau = -mgd \sin \theta \quad \text{and} \quad \tau = I\alpha$$

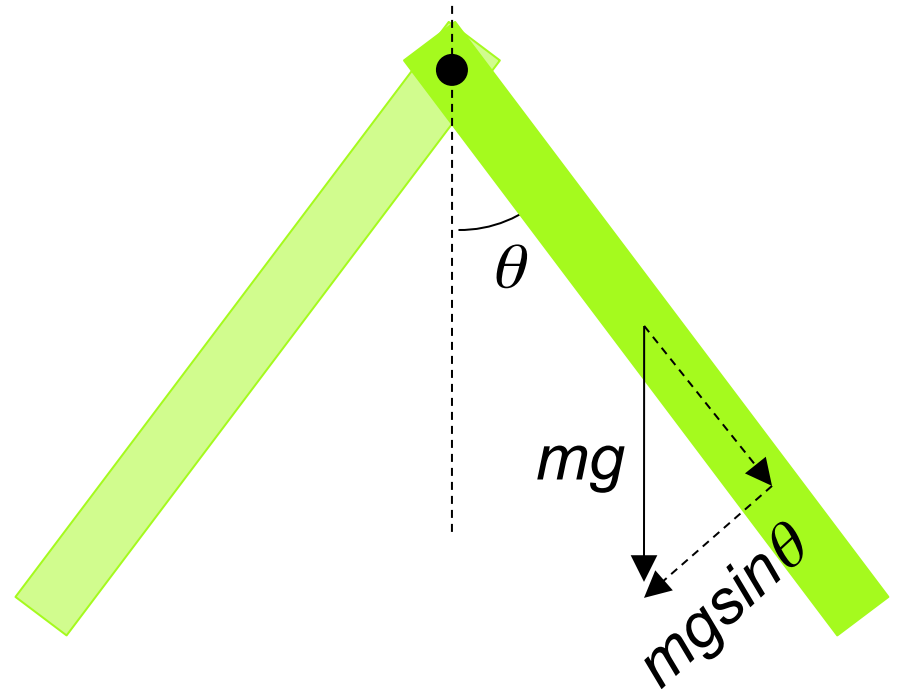
$$-mgd \sin \theta = I\alpha$$

$$-mgd \sin \theta = I \frac{d^2 \theta}{dt^2}$$

Assuming small θ :

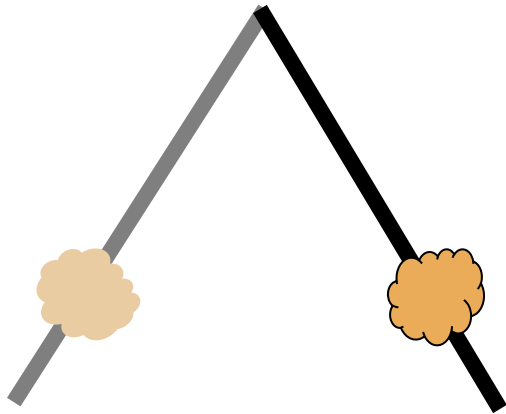
$$\frac{d^2 \theta}{dt^2} = \frac{-mgd \theta}{I}, \quad \text{so} \quad \omega = \sqrt{\frac{mgd}{I}}$$

(where d = distance from rotation axis to cg)



Example 3

A pendulum is made of a 1-kg meter stick with a 2-kg blob of clay stuck on it at the 75-cm mark.



a. What is the moment of inertia of this pendulum?

$$I_{total} = I_{stick} + I_{bob} = \frac{1}{3}ML^2 + MR^2$$

$$I = \frac{1}{3}(1kg)(1m)^2 + (2kg)(0.75m)^2$$

$$I = 1.46kg \cdot m^2$$

b. Where is the pendulum arm's center of mass located?

$$x_{cm} = \frac{1}{M}(x_1m_1 + x_2m_2)$$

$$x_{cm} = \frac{1}{3kg}((0.5m)(1kg) + (0.75m)(2kg))$$

$$x_{cm} = 0.67m$$

c. What is the period of the pendulum as it swings from an axis at the top end?

$$\omega = \sqrt{\frac{mgd}{I}} \text{ (from previous page)}$$

$$T = \frac{2\pi}{\omega} = 2\pi\sqrt{\frac{I}{mgd}} \dots$$

Ch 10-11 Test

Test average 2015-2016: 67.5%

Test average 2014-2015: 77.3%

Test average 2013-2014: 71.1%

Test average 2012-2013: 77.6%

HW Stats for 2012-2013:

Avg for stdnts regularly completing homework: 83.3%

Avg for stdnts with late or missing assignments: 71.6%

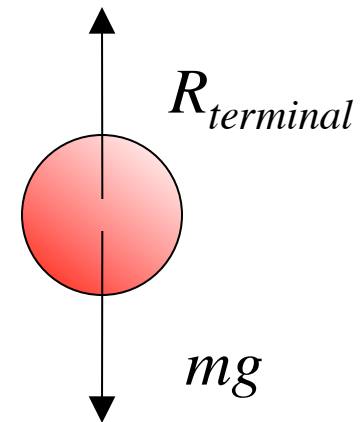
Test average 2011-2012: 79.9%

Test average 2010-2011: 69.7%

Finklebottom & Priest

“In the presence of air friction, objects accelerate at a constant rate $k < g$.”

If this is the case, what will the graph of x vs. t look like for an object falling in air? Is this what we actually observe?



Two common models of air friction. Which behavior is the cotton exhibiting? How could you find out?

$$R = -bv$$

or

$$R = \frac{1}{2} D \rho v^2$$

$$R \propto v$$

or

$$R \propto v^2$$

Graphing exercise

1. Set calculator mode to radians, and Standard Zoom on graph window
2. Graph $x=A \cos(\omega t+\phi)$ as $y1=4 \cos (1x+0)$
3. Graph $v=-\omega A \sin(\omega t+\phi)$ as $y2=-1\cdot 4\cdot \sin(1x+0)$
4. Graph a as well.

NOTES

1. x , v , and a all vary sinusoidally with time, but are not “in phase”
2. a is proportional to x , but in the opposite direction
3. f and T are independent of A